

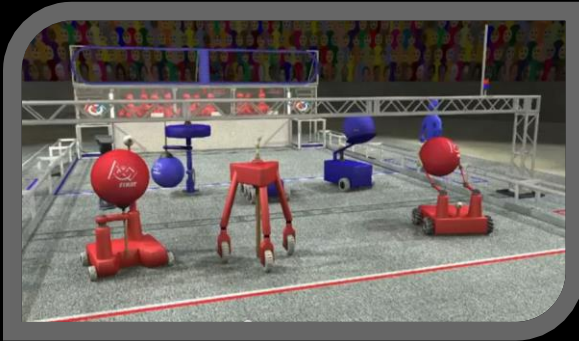


# Team Neutrino

## Newsletter Week #1

### Kickoff

Team Neutrino was excited to watch the global broadcast at this year's [kickoff](#) and game, Aerial Assist, on January 4<sup>th</sup>. We were a bit shocked at how FIRST could come up with such a unique game, but we started reading the rules and brainstorming strategies right away.



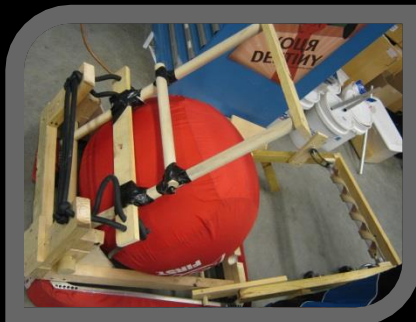
### Aerial Assist

[Aerial Assist](#) is played on a 25' x 54' field. Alliances of three robots each will compete by shooting their ball into their respective goals. There are two 10-point goals and six 1-point goals for each alliance. Robots will assist each other as they try to pass the ball down the field into one of the goals.



### Brainstorming

On Saturday, we started brainstorming by figuring out which strategies would score the most points. Then, on Monday, we brainstormed shooter designs, and came up with a catapult and a slingshot idea. We also thought of several pickup ideas, which we also started prototyping.



### Prototyping

Thanks to our access to Boyd lab at ISU, we were able to start prototyping this week. We built working wooden models of two of our shooter ideas, and a pickup idea that we can modify. One of our prototypes can be seen in the picture to the left.

**Coming Next Week:** Next week, we hope to continue CADD'ing, and continue our design process.

