The ROBRIC

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| **Trait** | **Bot #1:**  **\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_** | **Bot #2:**  **\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_** | **Bot #3:**  **\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_** | **Bot #4:**  **\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_\_** |
| speed |  |  |  |  |
| all terrain/over  barriers |  |  |  |  |
| ease of turning |  |  |  |  |
| precision |  |  |  |  |
| balance/stability |  |  |  |  |
| compact size |  |  |  |  |
| ease of adding attachments, sensors, motors |  |  |  |  |
| strength/power |  |  |  |  |
|  |  |  |  |  |